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Thread 3 aims to bring companion robots into the real-world by developing **use cases**, exploring **new interaction methods**, and designing the entire **lifecycle of use**.



Research Thread 3: Building Companion Robots for Long-Term Interaction

CHI 2017, SCIENCE ROBOTICS
POPULAR MECHANICS
HRI 2023, IDC 2022 BEST PAPER AWARD



Understanding “unboxing” robotic products



Designing novel “unboxing” experiences



Building social companions for long-term interaction



Studying long-term interaction through deployments