



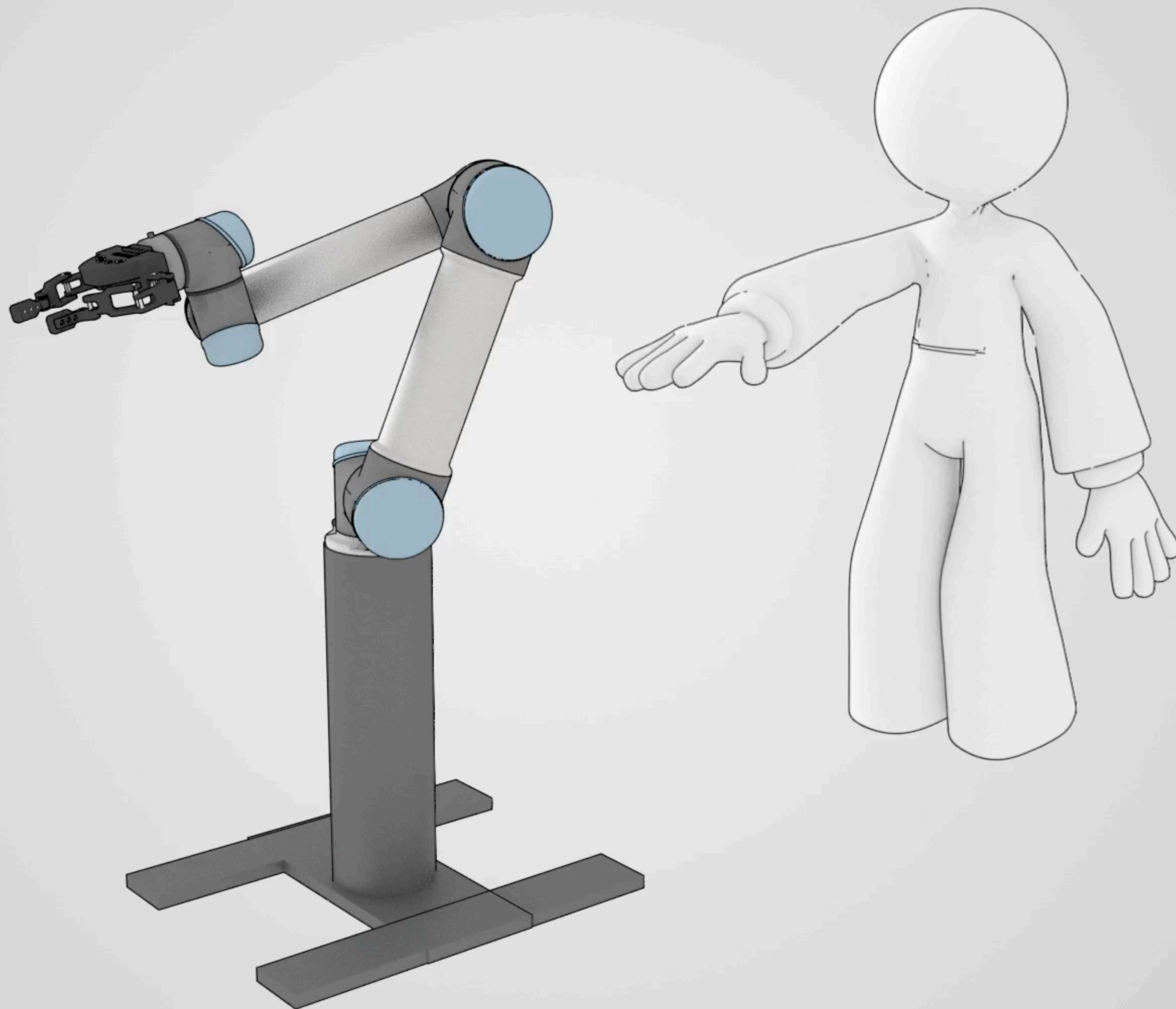




**Area 1:**

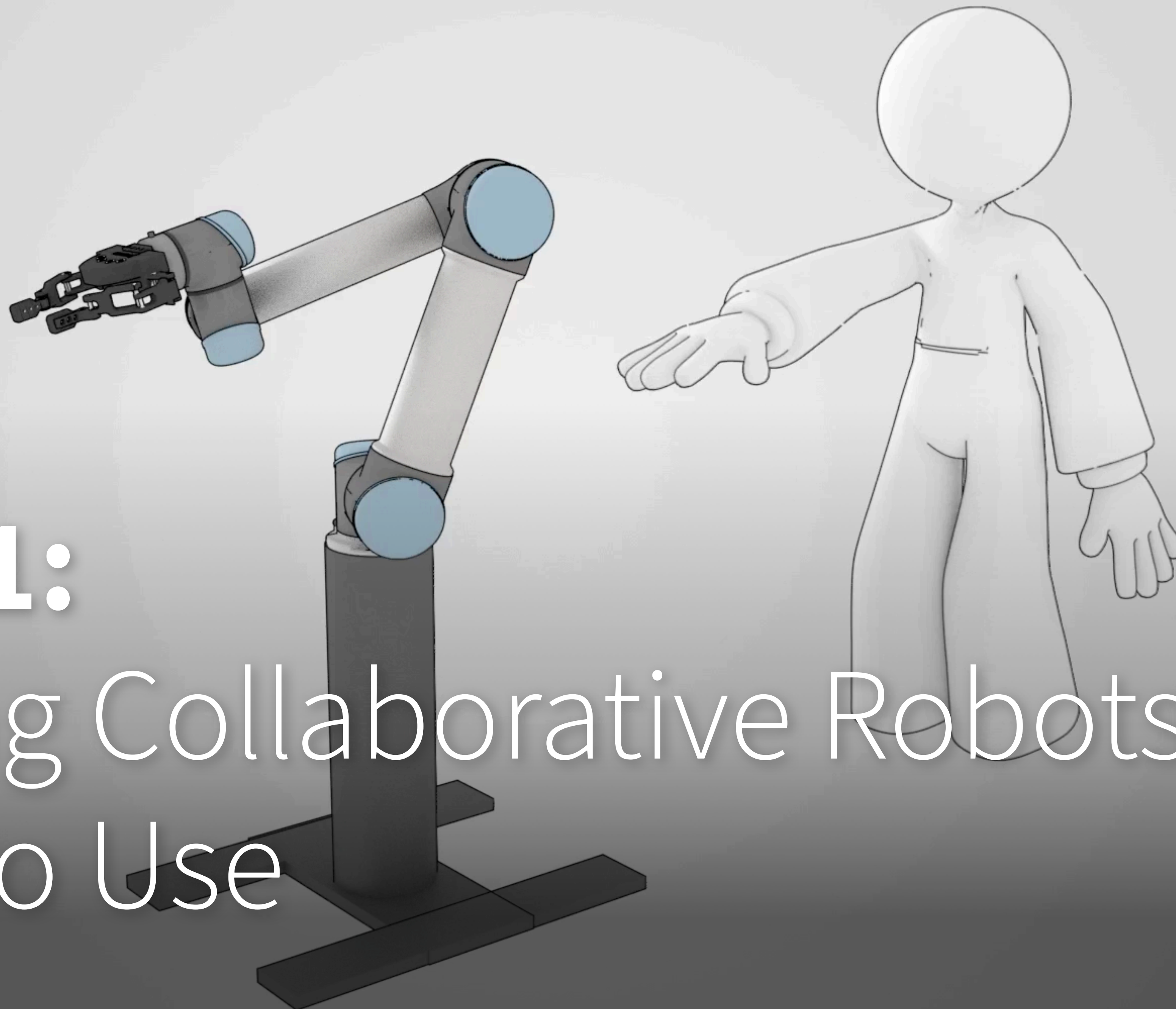
Making Collaborative Robots  
Easy to Use

**1**





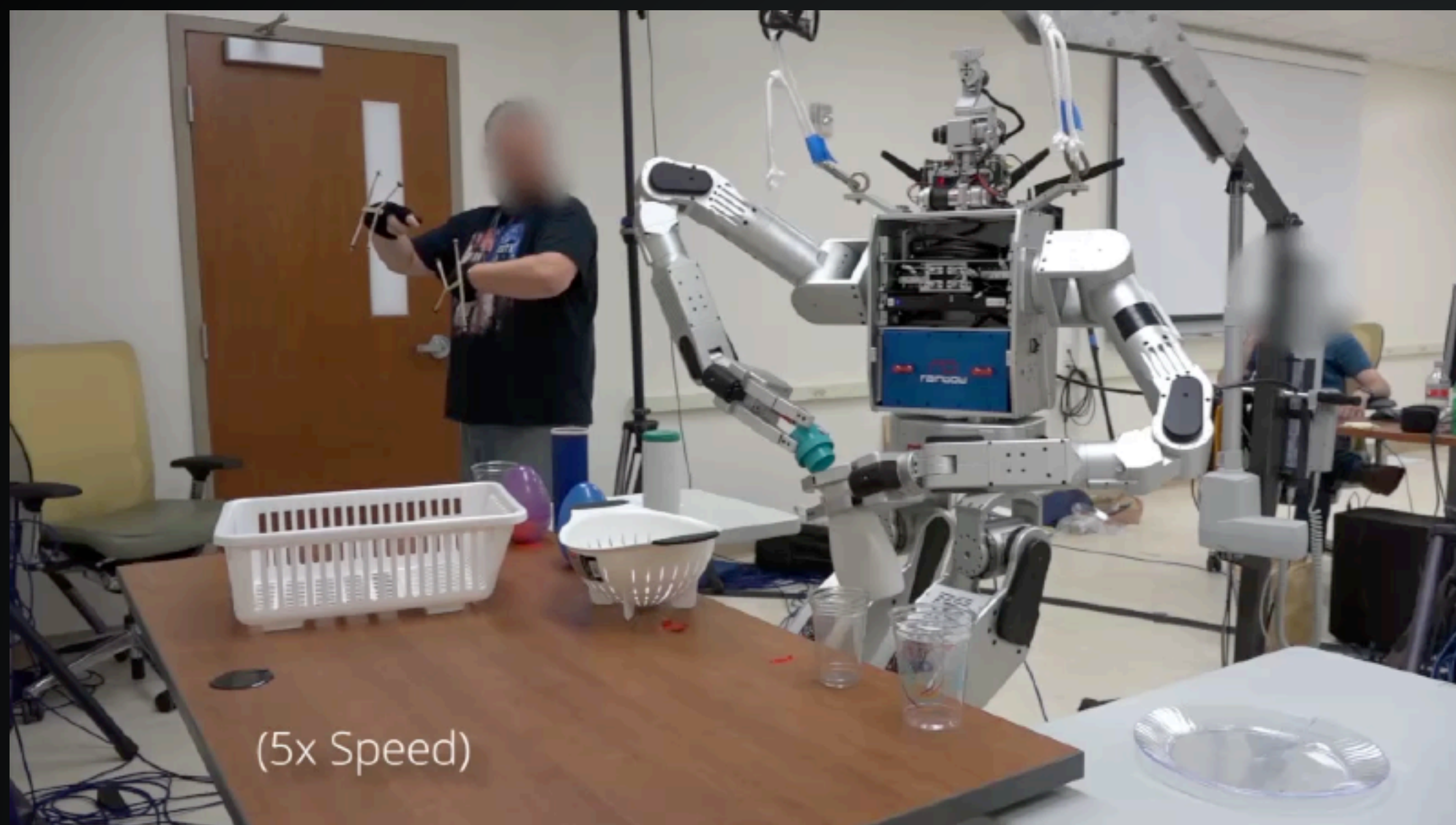
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## Area 1:

Making Collaborative Robots  
Easy to Use





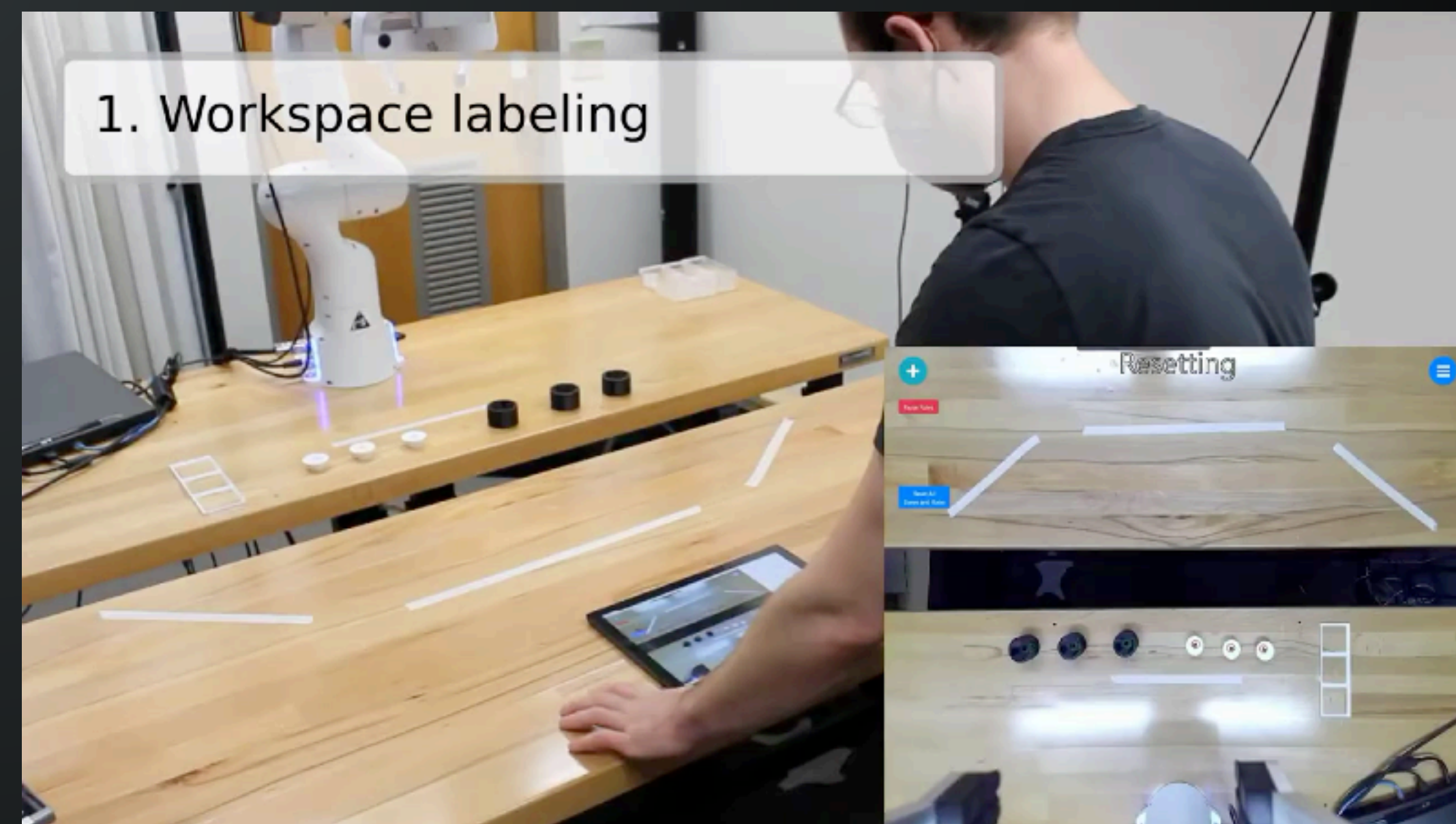
# Shared-control-based bimanual teleoperation



## Corrective shared control for highly variable tasks



## Task-level authoring for highly variable tasks



# Trigger-action-based plans for human-robot collaboration